

概率图模型理论及应用

Theory and Applications of Probabilistic Graphical Models
(Lesson 7 – Maximum Likelihood)

欧智坚

清华大学电子工程系

Addr: 罗姆楼 6-104

Tel: 62796193

Email: ozj@tsinghua.edu.cn

课程章节

❖ 第一章 图模型的表示理论 (2)

- Semantics (DGM, UGM)
- HMM, CRF

❖ 第二章 图模型的推理理论 (4)

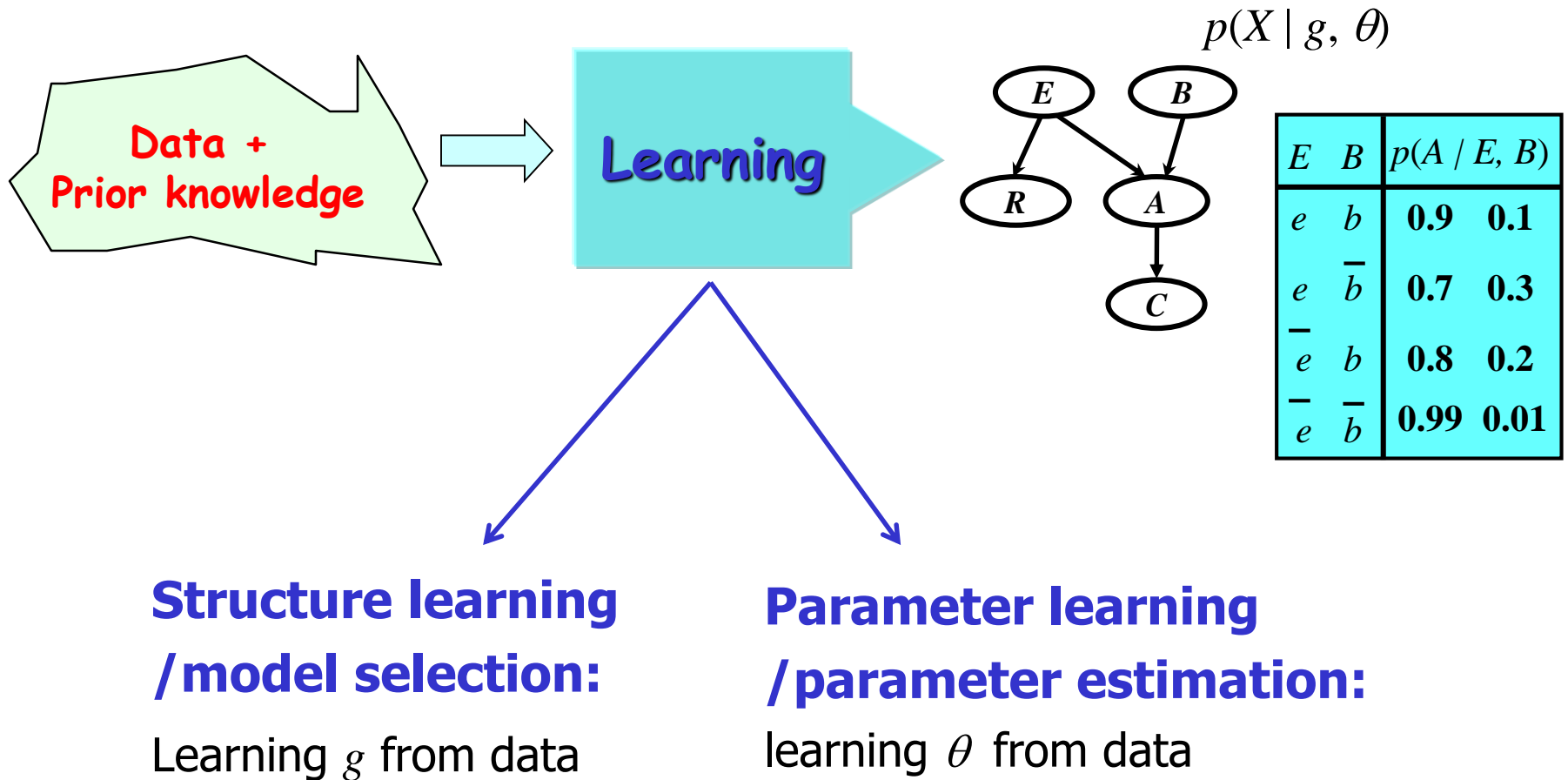
- 精确推理: **variable-elimination, cluster-tree, triangulate**
- 连续变量: **Kalman**
- 采样近似: **sampling**
- 变分近似: **variational**

❖ 第三章 图模型的学习理论 (2)

- 参数学习: **maxlikelihoodEstimate, RFLearning, BayesEstimate**
- 结构学习: **StructureLearning**

			pgm-2 hmm-crf ✓	pgm-4 kalman ✓
	pgm-1 semantics ✓		pgm-3 exact ✓	pgm-5 sampling ✓
pgm-6 variational ✓	pgm-8 Bayesian			
pgm-7 ML				

Learning



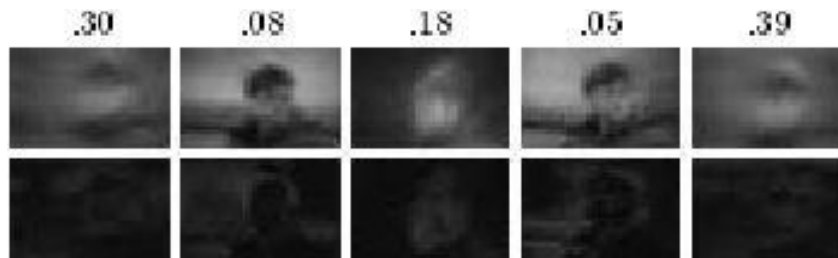
Data

- ❖ 总体分布 $p(x_{1:N} | g, \theta)$ 的一个个样本构成样本集/观测数据 $D = (x[1], \dots, x[M])$
 - 一个样本 $x_{1:N}[m] = (x_1[m], x_2[m], \dots, x_N[m])$
 - 独立同分布采样 (IID) : assume $x[1], \dots, x[M]$ are Independent and Identically Distributed $\sim p(x | g, \theta)$.
- ❖ 目标: 从 $D = (x[1], \dots, x[m], \dots, x[M])$ 中估计出 g, θ

总体分布: $p(x_1, x_2 | g, \theta)$, 其中 $w_k = p(x_1 = k)$ $p(x_2 | x_1 = k) = N(x | \mu_k, \Sigma_k)$

头姿类别 $x_1 \in 1:K$

观测图像 $x_2 \in R^{44 \times 28}$



$x[1]$

参数: $\theta = \{w_k, \mu_k, \Sigma_k, k = 1, \dots, K\}$

$x[5]$

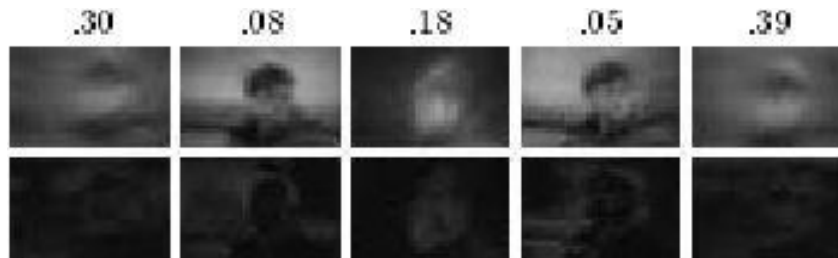
	x_1	x_2
$x[1]$	斜脸	
	侧脸	
	斜脸	
	斜脸	
$x[5]$	正脸	

Data — complete, incomplete

总体分布: $p(x_1, x_2 | g, \theta)$, 其中 $w_k = p(x_1 = k)$ $p(x_2 | x_1 = k) = N(x | \mu_k, \Sigma_k)$

头姿类别 $x_1 \in 1:K$

观测图像 $x_2 \in R^{44 \times 28}$



$x[1]$

x_1	x_2
斜脸	
侧脸	
斜脸	
斜脸	
正脸	

$x[5]$

参数: $\theta = \{w_k, \mu_k, \Sigma_k, k = 1, \dots, K\}$

数据: 400 幅图像及其头姿类别, $D = (x[1], \dots, x[400])$

- 完备数据: 样本中各变量都赋值
- 不完备数据:
 - latent/hidden variables: 样本中某些变量的取值未知

The learning problem

参数学习

结构学习

	Known structure	Unknown structure
Complete data	ML	Bayesian
Incomplete data	ML	Bayesian

DGMs, UGMs

Parameter learning

— ML (Known structure, complete data)

对单个分布的参数进行估计？

对一个贝叶斯网络的全体参数进行估计？

最大似然参数估计 (MLE)

给定一个概率分布的参数表达式 (parametric form)

记为 $p_{\theta}(x)$ 或 $p(x | \theta)$

从独立同分布样本集 $D = (x[1], \dots, x[M])$ 中估计出参数 θ ?



- $x \in \{1, 2, \dots, K\}$ is discrete r.v.
- $\theta_k = p(x=k), 1 \leq k \leq K$, is the parameters, $\theta = \{\theta_k | 1 \leq k \leq K\}$
- x is Gauss r.v. $X \sim N(\mu, \Sigma)$
- $\theta = (\mu, \Sigma)$ is the parameters

Multinomial distribution

- $x \in \{1, 2, \dots, K\}$ is discrete r.v.
- $\theta_k = p(x=k)$, $1 \leq k \leq K$, is the parameters, $\theta = \{\theta_k \mid 1 \leq k \leq K\}$
- 观测到独立同分布样本集 $D = (x[1], \dots, x[M])$
- 希望估计 θ ?



$$\text{似然函数 } p(x[1:M] | \theta) = \prod_{m=1}^M p(x[m] | \theta) = \prod_{k=1}^K \theta_k^{N_k}$$

N_k : 在样本集中 $x[m]=k$ 出现的次数

$$\text{最大似然估计 } \theta_k^{ML} = \frac{N_k}{\sum_{l=1}^K N_l}$$

(N_1, \dots, N_K) are sufficient statistics

Sufficient statistics

- ❖ 统计量：样本集 $D = (x[1], \dots, x[M])$ 的某函数
- ❖ Neyman Factorization theorem
一个统计量 $s(D)$, i.e., $s(x[1], \dots, x[M])$ 是充分统计量当且仅当 似然函数可以如下分解：

$$p(D | \theta) = g(\theta, s(D)) \cdot h(D)$$

参数与样本的关联 完全通过充分统计量来体现

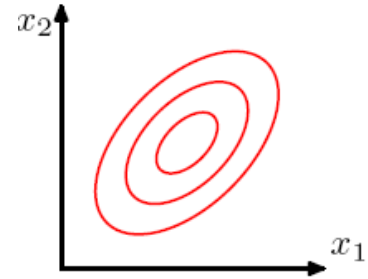
$$p(D | \theta) = \prod_{m=1}^M p(x[m] | \theta) = \prod_{k=1}^K \theta_k^{N_k}$$

N_k : 在样本集中 $x[m]=k$ 出现的次数



Gauss distribution

- x is Gauss r.v. $X \sim N(\mu, \Sigma)$
- $\theta = (\mu, \Sigma)$ is the parameters
- 观测到独立同分布样本集 $D = (x[1], \dots, x[M])$
- 希望估计 θ ?



$$p(x | \theta) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp \left[-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right]$$

对数似然函数

$$\log p(x[1:M] | \mu, \Sigma) = \sum_{m=1}^M \log p(x[m] | \mu, \Sigma)$$

$$\max_{\mu, \Sigma} = -\frac{Md}{2} \log(2\pi) - \frac{M}{2} \left\{ \log |\Sigma| + \text{tr}(\Sigma^{-1} \bar{\Sigma}) + (\bar{\mu} - \mu) \Sigma^{-1} (\bar{\mu} - \mu)^T \right\}$$

$$\begin{cases} \frac{\partial L}{\partial \mu} = M \cdot \Sigma^{-1} (\bar{\mu} - \mu) = 0 \\ \frac{\partial L}{\partial \Sigma^{-1}} = -\frac{M}{2} \cdot \left\{ -\Sigma + \bar{\Sigma} + (\bar{\mu} - \mu)(\bar{\mu} - \mu)^T \right\} = 0 \end{cases} \quad \Rightarrow \quad \begin{cases} \bar{\mu} = \frac{1}{M} \sum_{m=1}^M x[m] \\ \bar{\Sigma} = \frac{1}{M} \sum_{m=1}^M (x[m] - \bar{\mu})(x[m] - \bar{\mu})^T \end{cases}$$

Learning parameters for BNs (complete data)

- 考虑贝叶斯网络 $X = \{X_1, X_2, \dots, X_N\}$
 假设：各个条件分布 $p(x_1 | pa_1), p(x_2 | pa_2), \dots, p(x_N | pa_N)$
 有各自表征参数 $\{\theta_1, \theta_2, \dots, \theta_N\} = \theta$

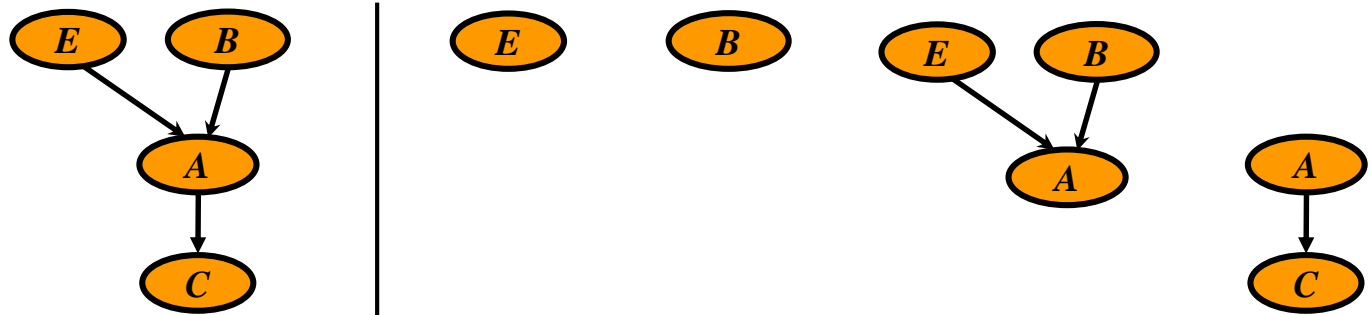
- IID样本集 $D = (x[1], \dots, x[M])$ 下似然函数

$$\max_{\theta} p(D | \theta) = \prod_{m=1}^M p(x[m] | \theta) = \prod_{m=1}^M \prod_{n=1}^N p(x_n[m] | pa_n[m], \theta_n) = \prod_{n=1}^N \max_{\theta_n} \prod_{m=1}^M p(x_n[m] | pa_n[m], \theta_n)$$

- 对每个条件分布 $p(x_n | pa_n)$ 分别估计其参数 θ_n

$$\hat{\theta}_n = \arg \max_{\theta_n} \prod_{m=1}^M p(x_n[m] | pa_n[m], \theta_n)$$

E, B, A, C
$\langle 1, 0, 0, 0 \rangle$
$\langle 1, 1, 1, 1 \rangle$
...
$\langle 1, 0, 1, 1 \rangle$

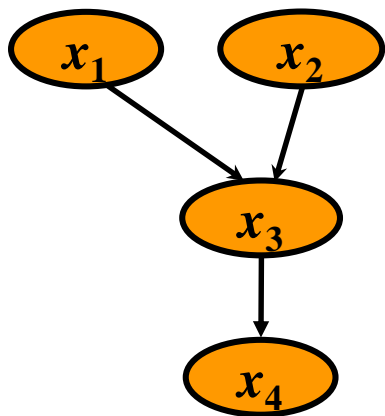


$$\max_{\theta} p(D | \theta) = \prod_{m=1}^M p(E[m] | \theta_1) p(B[m] | \theta_2) p(A[m] | E[m], B[m], \theta_3) p(C[m] | A[m], \theta_4)$$

$$\left. \left\{ \max_{\theta_1} \prod_{m=1}^M p(E[m] | \theta_1), \max_{\theta_2} \prod_{m=1}^M p(B[m] | \theta_2), \max_{\theta_3} \prod_{m=1}^M p(A[m] | E[m], B[m], \theta_3), \max_{\theta_4} \prod_{m=1}^M p(C[m] | A[m], \theta_4) \right\} \right\} 13$$

Example: Multinomial Bayes net

- 假设变量 X_n 有 K_n 个不同可能取值
- 结点 x_n 的条件分布 $p(x_n | pa_n)$ 含有一系列多元分布。对父结点集 pa_n 的每个可能取值组合 i ，有一个多元分布 $p(x_n | pa_n = i)$
- $\theta = \{\theta_n | n = 1, \dots, N\}$ $\theta_n = \{\theta_{n,i} | i = 1, \dots\}$ $\theta_{n,i} = \{\theta_{n,i,k} | k = 1, \dots, K_n\}$

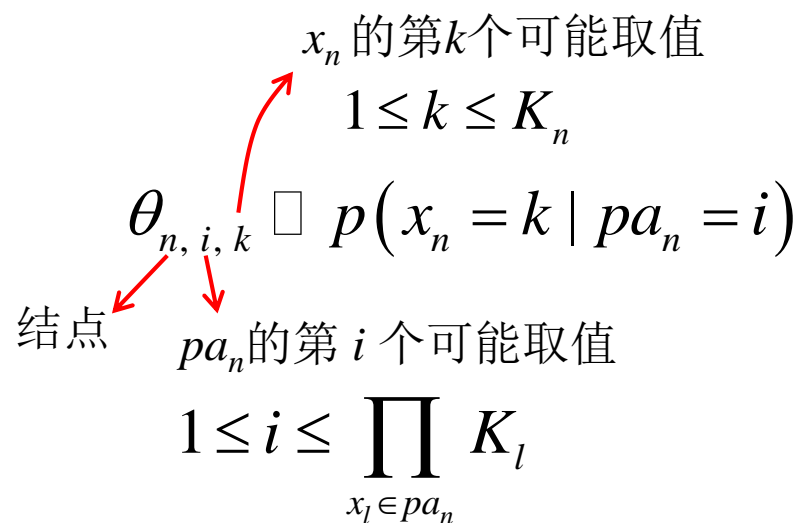


$$p(x_3 | pa_3 = (0,0))$$

$$p(x_3 | pa_3 = (0,1))$$

$$p(x_3 | pa_3 = (1,0))$$

$$p(x_3 | pa_3 = (1,1))$$



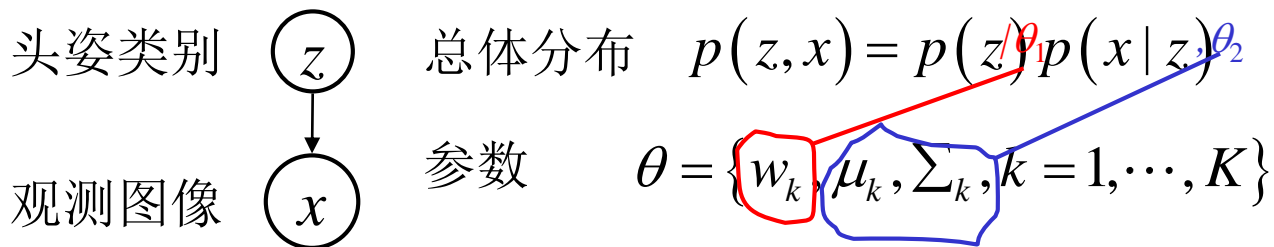
Example: MLE for multinomial Bayes net

- 似然函数 $p(x_n[1:M] | \theta_n) \square \prod_{m=1}^M p(x_n[m] | pa_n[m], \theta_n)$
$$= \prod_i \prod_k (\theta_{n,i,k})^{N_{n,i,k}}$$

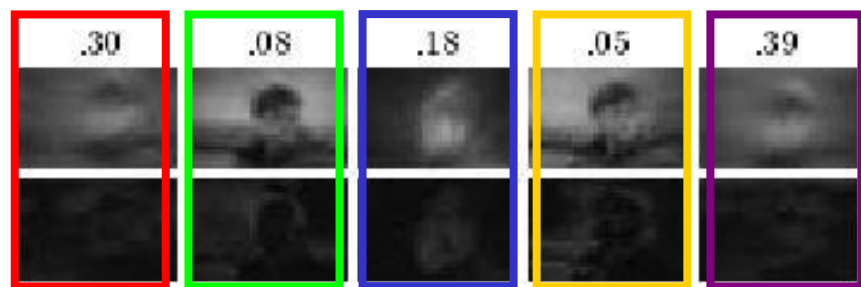
- 充分统计量 $N_{n,i,k} \square \sum_{m=1}^M 1(pa_n[m] = i, x_n[m] = k)$

- 最大似然估计:
$$\hat{\theta}_{n,i,k} = \frac{N_{n,i,k}}{\sum_{l=1}^{K_n} N_{n,i,l}}$$

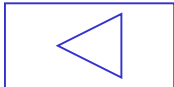
高斯混合模型—完备数据



参数估计

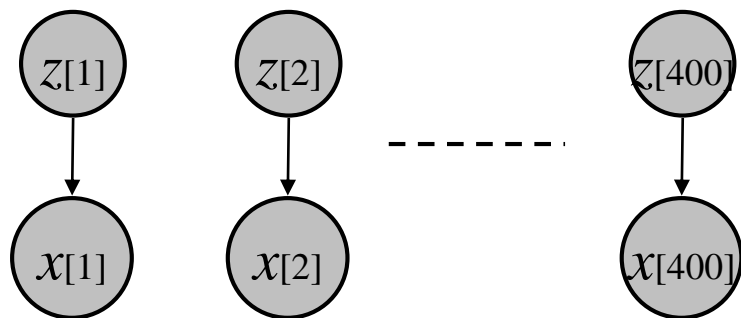


400 幅图像及其头姿类别标注
 完备数据 $D = \left(\left(\begin{matrix} x[1] \\ z[1] \end{matrix} \right), \dots, \left(\begin{matrix} x[400] \\ z[400] \end{matrix} \right) \right)$



高斯混合模型—完备数据

$$\theta = \{w_k, \mu_k, \Sigma_k, k = 1, \dots, K\}$$



$$\log p(x[1:M], z[1:M] | \theta)$$

$$= \sum \log p(x[m], z[m] | \theta)$$

$$= \sum_m \left[\log p(z[m] | \theta) + \log p(x[m] | z[m], \theta) \right]$$

$$= \sum_m \log p(z[m] | w_{1:K}) + \sum_m \log N(x[m] | \mu_{z[m]}, \Sigma_{z[m]})$$

$$\sum_{k=1}^K \sum_{m: z[m]=k} \log w_k$$

(A blue arrow points from the first sum in the previous equation to this one.)

$$\sum_{k=1}^K \sum_{m: z[m]=k} \log N(x[m] | \mu_k, \Sigma_k)$$

(A green arrow points from the second sum in the previous equation to this one.)

离散变量 z 的400个样本下的对数似然值,

对第 k 类, 高斯变量 x 的

N_k 个样本下的对数似然值,

$$\mu_k^{ML}, \Sigma_k^{ML}$$

$$w_k^{ML} = \frac{N_k}{M}$$

$$= \frac{1}{M} \sum_{m=1}^M 1(z[m]=k)$$

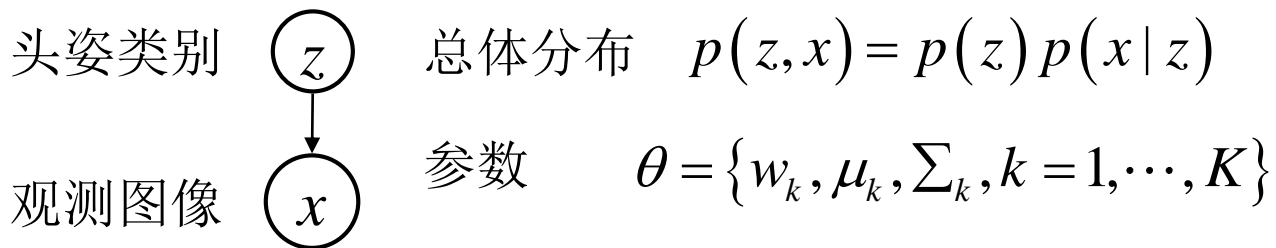
$$\begin{cases} \bar{\mu}_k^{ML} = \frac{1}{N_k} \sum_{m: z[m]=k} x[m] \\ \bar{\Sigma}_k^{ML} = \frac{1}{N_k} \sum_{m: z[m]=k} (x[m] - \bar{\mu}_k^{ML})(x[m] - \bar{\mu}_k^{ML})^T \end{cases}$$

Parameter learning

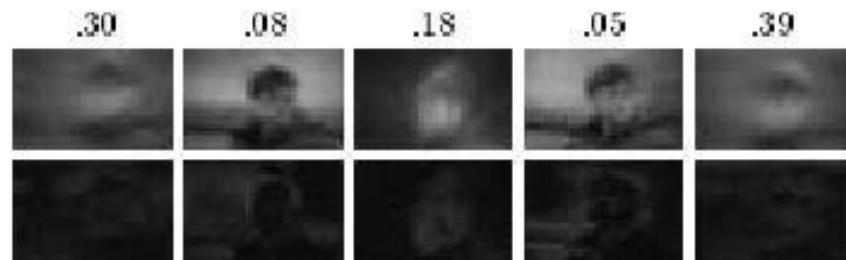
— ML (Known structure, incomplete data)

Expectation-Maximization 算法

高斯混合模型—不完备数据



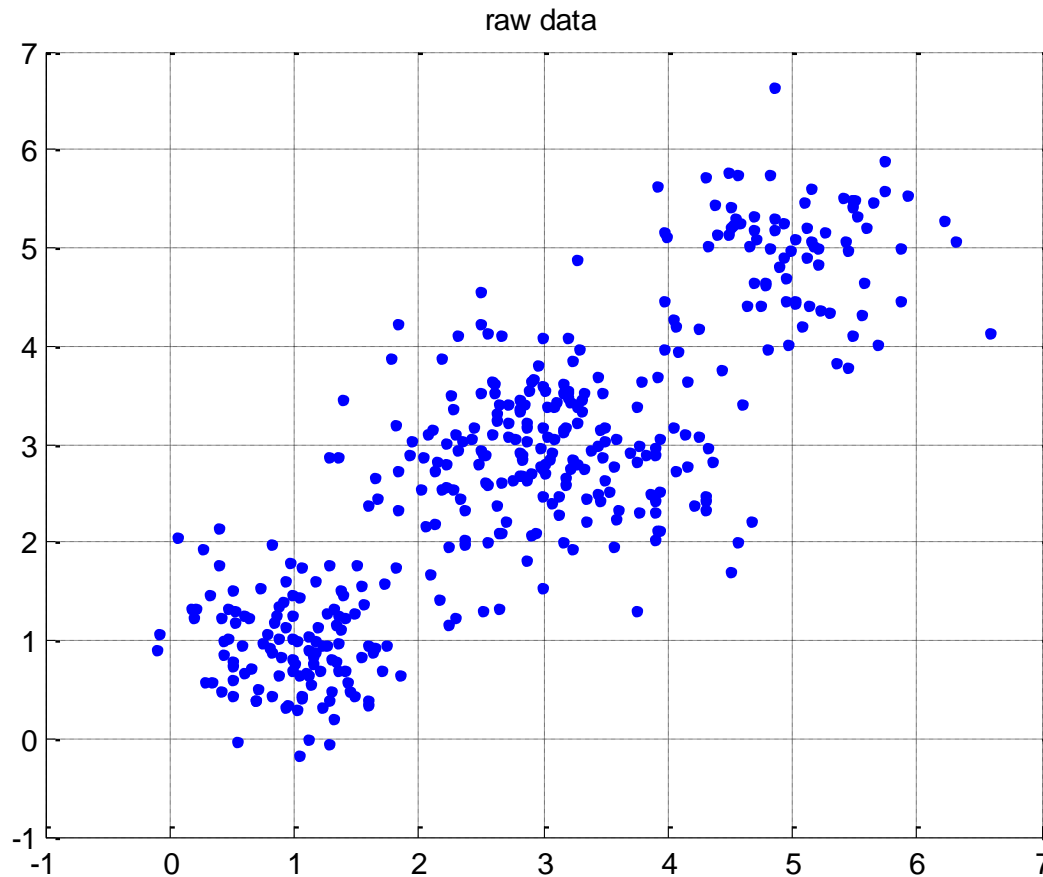
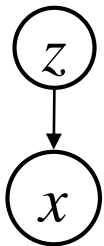
参数估计



数据: 400 幅图像 $D = (x[1], \dots, x[400])$

不完备数据

Homework3_em



```
function [weight, meanvec, stdvec] = EmEstimate(x, iternum)
% x is the input observation, D-dim vectors * N
% iternum is the given number for EM iterations
```

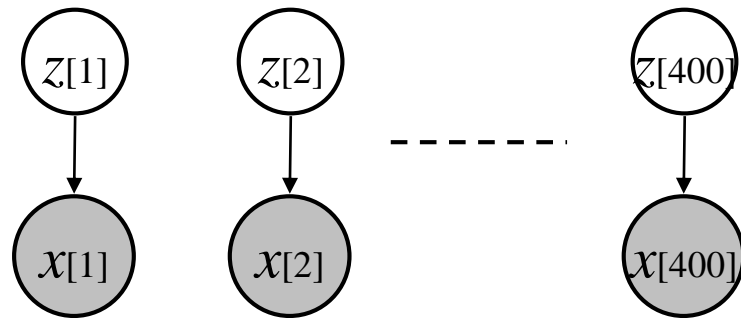
高斯混合模型—不完备数据

$$\theta = \{w_k, \mu_k, \Sigma_k, k = 1, \dots, K\}$$

$$\log p(x[1:M] | \theta)$$

$$= \sum_m \log p(x[m] | \theta)$$

$$\stackrel{\text{m}}{\text{a}} \sum_m \log \left(\sum_k w_k N(x[m] | \mu_k, \Sigma_k) \right)$$



$$\frac{\partial}{\partial w_k} \log p(x[1:M] | \theta) = \sum_m \frac{\partial}{\partial w_k} \log \left(\sum_k w_k N(x[m] | \mu_k, \Sigma_k) \right)$$

$$= \sum_m \frac{1}{\sum_k w_k N(x[m] | \mu_k, \Sigma_k)} \frac{\partial}{\partial w_k} \left(\sum_k w_k N(x[m] | \mu_k, \Sigma_k) \right)$$

$$\frac{\partial}{\partial \mu_k} \log p(x[1:M] | \theta) =$$

$$\frac{\partial}{\partial \Sigma_k} \log p(x[1:M] | \theta) =$$

需要求解

$$\theta = \{w_k, \mu_k, \Sigma_k, k = 1, \dots, K\}$$

联立非线性方程!

EM一般讨论

❖ 记 x 为全体观测值，记 z 为全体隐变量

■ 联合分布： $p(x, z | \theta)$

$$\theta^{ML} = \arg \max_{\theta} \log p(x | \theta)$$

$$= \log \sum_z p(x, z | \theta)$$

❖ $\log p(\overset{z}{x} | \theta)$ is called the incomplete log-likelihood.

■ 联合分布 $p(x, z | \theta)$ 的分解表示得不到利用

❖ $\log p(x, z | \theta)$ is called the complete log-likelihood.

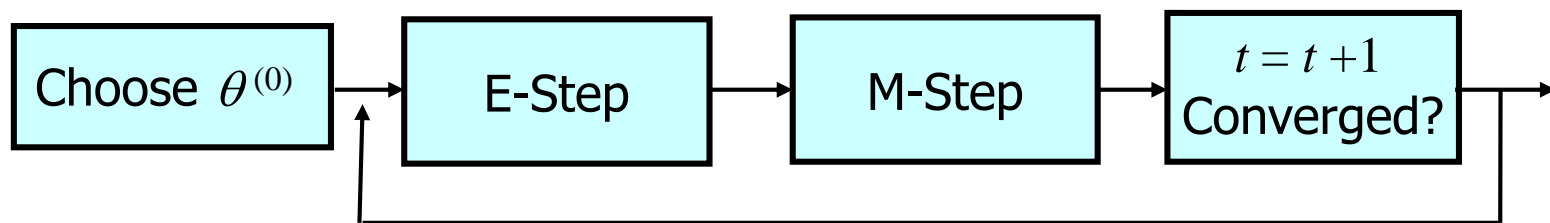
■ 利用分解

EM算法描述

- ❖ z 是隐变量，完备对数似然函数 $\log p(x, z | \theta)$ 是 z 的一个函数
- ❖ 使用 完备对数似然函数的期望？
- ❖ 完备对数似然函数 $\log p(x, z | \theta)$ 在条件分布 $p(z | \theta^{old}, x)$ 下的期望

$$Q(\theta | \theta^{old}) = E[\log p(x, z | \theta) | \theta^{old}, x] = \sum_z p(z | \theta^{old}, x) \log p(x, z | \theta)$$

- ❖ 求解 $\theta^* = \arg \max_{\theta} Q(\theta | \theta^{old})$
成立 $\log p(x | \theta^{old}) \leq \log p(x | \theta^*)$
- ❖ EM算法是一个迭代过程



Jensen Inequality : for convex \cap function f

$$E[f(U)] \leq f(E[U])$$

EM算法证明

$$\log p(x, z | \theta) = \log p(x | \theta) + \log p(z | \theta, x), \quad \forall \theta \text{ applying } E[\dots | \theta^{(old)}, x]$$

$$E[\log p(x, z | \theta) | \theta^{(old)}, x] = \log p(x | \theta) + E[\log p(z | \theta, x) | \theta^{(old)}, x], \quad \forall \theta$$

$$E[\log p(x, z | \theta^{(old)}) | \theta^{(old)}, x] = \log p(x | \theta^{(old)}) + E[\log p(z | \theta^{(old)}, x) | \theta^{(old)}, x]$$

$$\begin{pmatrix} E[\log p(x, z | \theta) | \theta^{(old)}, x] \\ -E[\log p(x, z | \theta^{(old)}) | \theta^{(old)}, x] \end{pmatrix} = \begin{pmatrix} \log p(x | \theta) \\ -\log p(x | \theta^{(old)}) \end{pmatrix} + E\left[\log \frac{p(z | \theta, x)}{p(z | \theta^{(old)}, x)} \mid \theta^{(old)}, x\right]$$

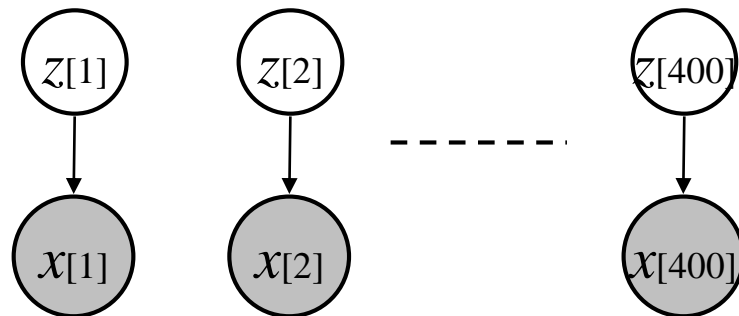
$$\begin{aligned} Q(\theta | \theta^{(old)}) &= E[\log p(x, z | \theta) | \theta^{(old)}, x] \leq \log E\left[\frac{p(z | \theta, x)}{p(z | \theta^{(old)}, x)} \mid \theta^{(old)}, x\right] \\ &= \log \sum_z \frac{p(z | \theta, x)}{p(z | \theta^{(old)}, x)} p(z | \theta^{(old)}, x) \end{aligned}$$

EM Example: Learning with GMM

$$Q(\theta | \theta^{(old)}) = E[\log p(x, z | \theta) | \theta^{(old)}, x]$$

❖ 给定不完备数据 $(x[1], \dots, x[M])$

$$E[\log p(x[1:M], z[1:M] | \theta) | \theta^{(old)}, x[1:M]]$$



$$= \sum_m E[\log p(x[m], z[m] | \theta) | \theta^{(old)}, x[1:M]]$$

$$= \sum_m \sum_{z[m]} p(z[m] | \theta^{(old)}, x[m]) \log p(x[m], z[m] | \theta)$$

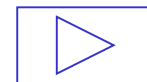
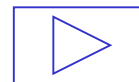
$$= \sum_m \sum_{z[m]} p(z[m] | \theta^{(old)}, x[m]) \{ \log p(x[m] | \theta, z[m]) + \log p(z[m] | \theta) \}$$

$$= \sum_m \sum_k p(z[m] = k | \theta^{(old)}, x[m]) \{ \log p(x[m] | \theta, z[m] = k) + \log p(z[m] = k | \theta) \}$$

$$\max_{\{w_k, \mu_k, \Sigma_k, k=1:K\}} \left\{ \sum_k \sum_m \gamma_m(k) \log N(x[m] | \mu_k, \Sigma_k) + \sum_k \sum_m \gamma_m(k) \log w_k \right\}$$

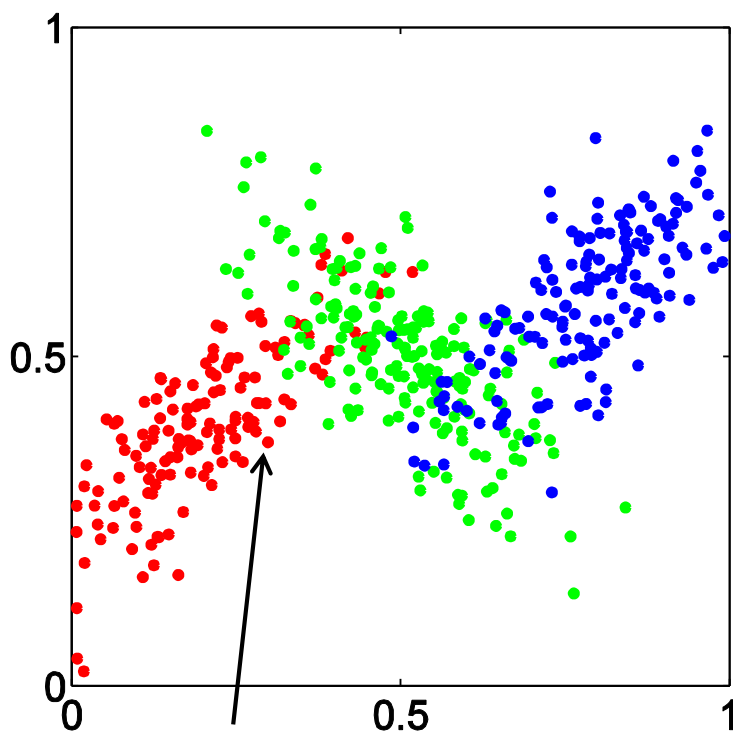
subject to: $\sum_k w_k = 1$

Posterior Probabilities

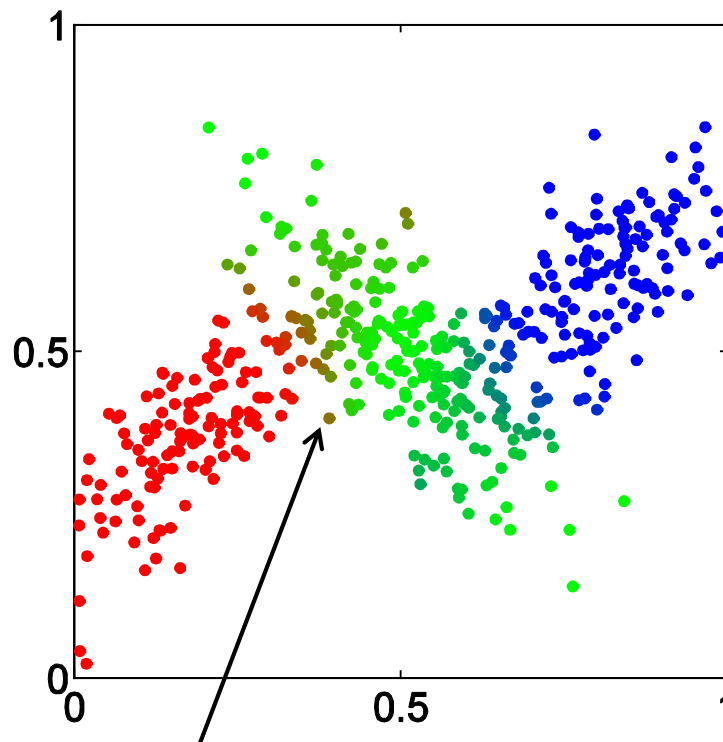


$\frac{m}{a}$ 不完备数据下目标函数 = $\sum_{k=1}^K \sum_{m=1}^M \gamma_m(k) \log N(x[m] | \mu_k, \Sigma_k) + \frac{m}{X} \sum_{k=1}^K \sum_{m=1}^M \gamma_m(k) \log w_k$

$\frac{m}{a}$ 完备数据下目标函数 = $\sum_{k=1}^K \sum_{m=1}^M 1(z[m] = k) \log N(x[m] | \mu_k, \Sigma_k) + \frac{m}{X} \sum_{k=1}^K \sum_{m=1}^M 1(z[m] = k) \log w_k$

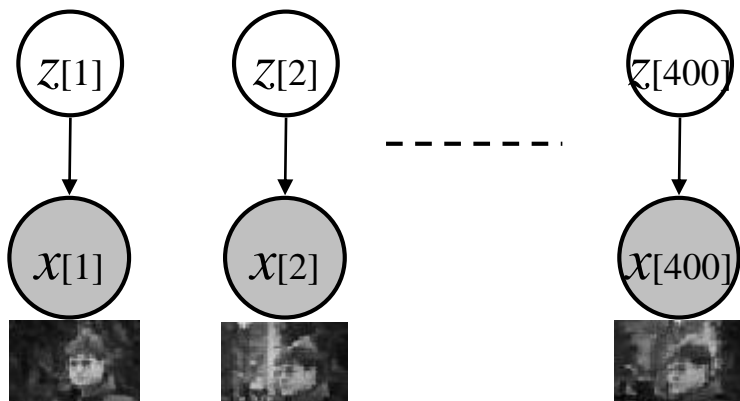
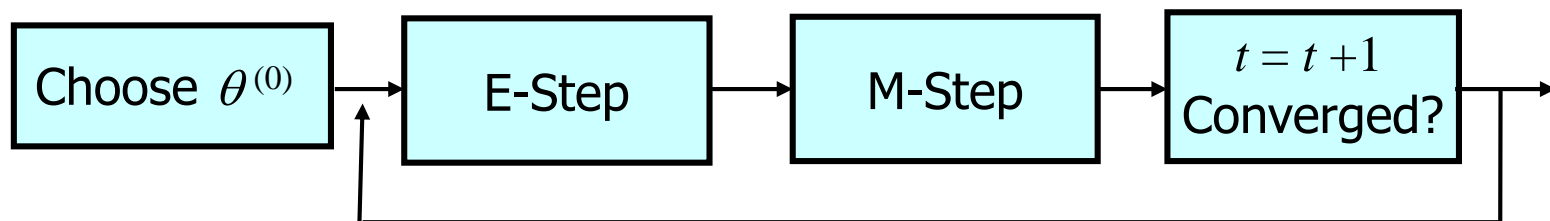


Hard assignment



Soft assignment

EM Example: Learning with GMM



$$\mu_k^* = \frac{\sum_m \gamma_m(k) x[m]}{\sum_m \gamma_m(k)} \quad \bar{\mu}_k^{ML} = \frac{\sum_{m=1}^M 1(z[m]=k) x[m]}{\sum_{m=1}^M 1(z[m]=k)}$$

$$\Sigma_k^* = \frac{\sum_m \gamma_m(k) (x[m] - \mu_k^*) (x[m] - \mu_k^*)^T}{\sum_m \gamma_m(k)}$$

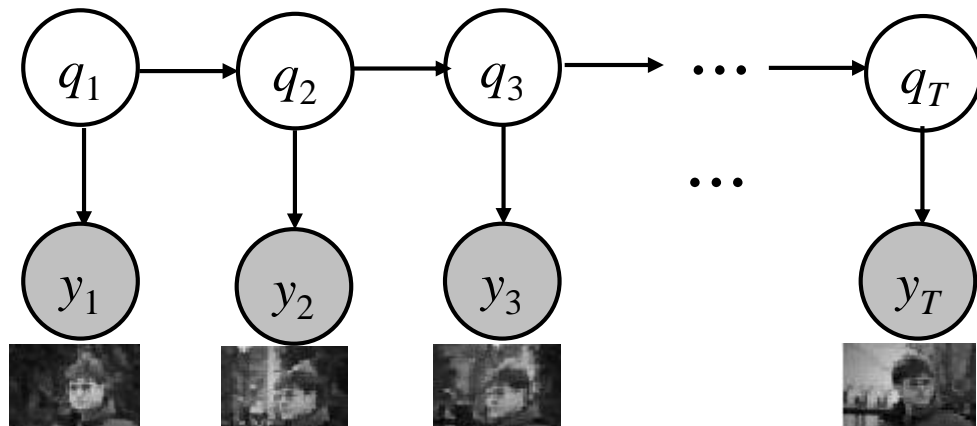
$$= \frac{\sum_m \gamma_m(k) x[m] x[m]^T}{\sum_m \gamma_m(k)} - \mu_k^* (\mu_k^*)^T$$

$$w_k^* = \frac{\sum_m \gamma_m(k)}{M}$$

$$\gamma_m(k) = p(z[m]=k | \theta^{(old)}, x[m])$$

$$= \frac{w_k^{(old)} N(x[m] | \mu_k^{(old)}, \Sigma_k^{(old)})}{\sum_k w_k^{(old)} N(x[m] | \mu_k^{(old)}, \Sigma_k^{(old)})}$$

EM Example: Learning with HMM



$$\lambda = (\pi, A, B) \quad \max_{\lambda} \log p(y_{1:T} | \lambda) ?$$

$$\lambda^* = \arg \max_{\lambda} E \left[\log p(y_{1:T}, q_{1:T} | \lambda) \mid \lambda^{(t)}, y_{1:T} \right]$$

$$= \arg \max_{\lambda} \left\{ \begin{array}{l} E \left[\log p(q_1 | \lambda) \mid \lambda^{(t)}, y_{1:T} \right] \\ + \sum_{t=2}^T E \left[\log p(q_t | \lambda, q_{t-1}) \mid \lambda^{(t)}, y_{1:T} \right] \\ + \sum_{t=1}^T E \left[\log p(y_t | \lambda, q_t) \mid \lambda^{(t)}, y_{1:T} \right] \end{array} \right\} \quad \leftarrow \begin{array}{l} \log p(y_{1:T}, q_{1:T} | \lambda) \\ = \log p(q_1 | \lambda) \\ + \sum_{t=2}^T \log p(q_t | \lambda, q_{t-1}) \\ + \sum_{t=1}^T \log p(y_t | \lambda, q_t) \end{array}$$

From EM to SA

❖ 记 x 为全体观测值，记 z 为全体隐变量

■ 联合分布: $p(x, z | \theta)$

$$\theta^{ML} = \arg \max_{\theta} \log p(x | \theta)$$

$$Q(\theta | \theta^{(old)}) = E[\log p(x, z | \theta) | \theta^{(old)}, x] = \sum_z p(z | \theta^{(old)}, x) \log p(x, z | \theta)$$

$$\text{Fisher Equality: } \frac{\partial \log p(x | \theta)}{\partial \theta} = E_{p(z|x, \theta)} \left[\frac{\partial \log p(x, z | \theta)}{\partial \theta} \right]$$

$$\therefore E_{p(z|x, \theta)} \left[\frac{\partial \log p(z | x, \theta)}{\partial \theta} \right] = 0$$

Problem: The objective is to find a solution θ to $E_{Y \sim f(\cdot; \theta)}[H(Y; \theta)] = \alpha$, where $\theta \in R^d$, noisy observation $H(Y; \theta) \in R^d$.

- Delyon, Lavielle, and Moulines. "Convergence of a stochastic approximation version of the EM algorithm." *Annals of statistics*, 1999.
- Zhijian Ou. "A Review of Learning with Deep Generative Models from Perspective of Graphical Modeling." arXiv:1808.01630.

UGM Semantics - Factorization property (F)

- ❖ A probability distribution $p(x_V)$ is said to **factorize** according to g , if there exist non-negative functions (called **potential functions**) $\phi_C(x_C)$ for all cliques C such that

$$p(x_V) = \frac{1}{Z} \prod_{C \in \mathcal{C}} \phi_C(x_C) \quad \text{or} \quad p(x_V) \propto \prod_{C \in \mathcal{C}} \phi_C(x_C)$$

where Z is the **normalizing constant** (partition function)

$$Z = \sum_{x_V} \prod_{C \in \mathcal{C}} \phi_C(x_C)$$

- Potential functions $\phi_C(x_C)$ are not uniquely determined.
- Without loss of generality, define potentials over maximum cliques.

Hammersley-Clifford Theorem: If p is strictly positive, (F) \Leftrightarrow (G).

UGMs and log-linear models

- ❖ Let each clique potential be a log-linear function

$$\log \phi_c(x_c) = \theta_c^T f_c(x_c)$$

where $f_c(x_c)$ is a [feature vector](#) derived from the values of the variables x_c , θ_c is the associated [feature weight vector](#).

- ❖ The resulting joint has the form

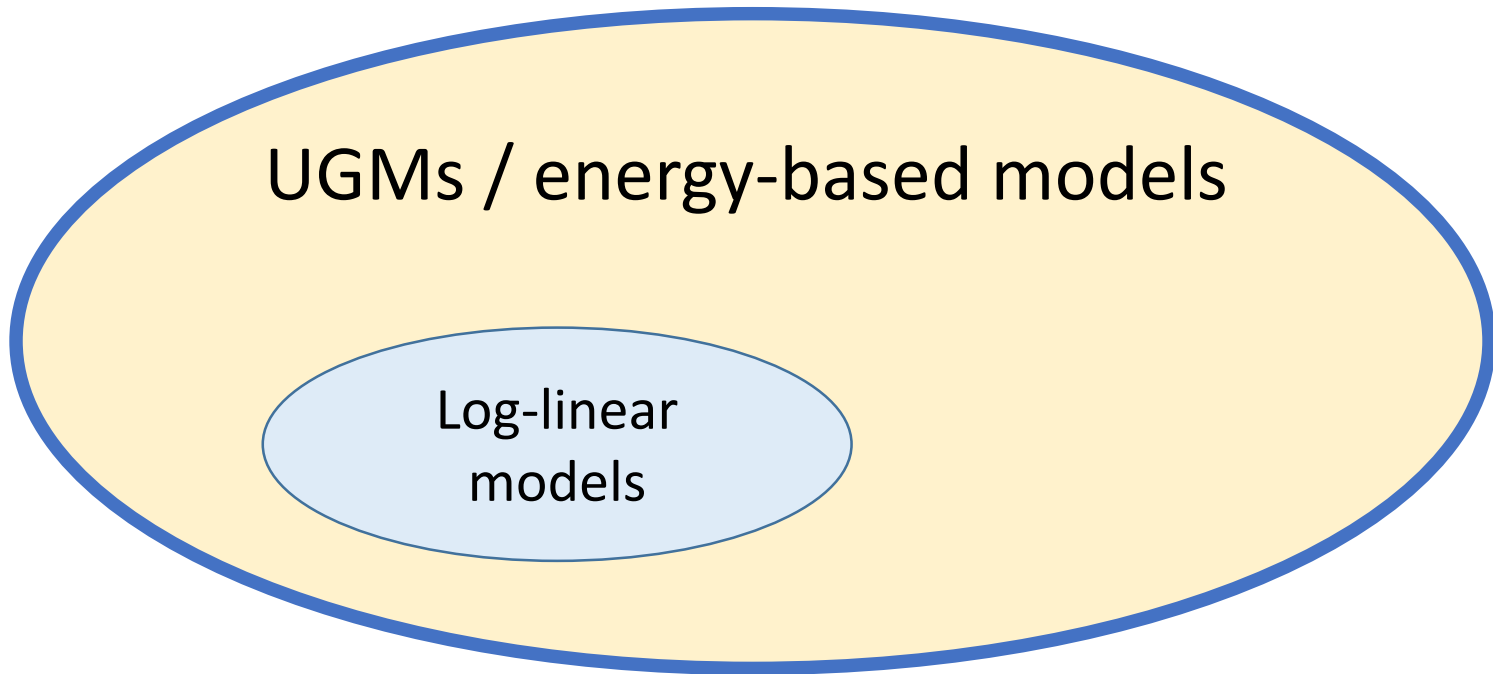
$$p(x_V) = \frac{1}{Z(\theta)} \exp \left[\sum_c \theta_c^T f_c(x_c) \right]$$

This is known as a [log-linear model](#) or a [Maximum Entropy model](#).

It can be proved that the maxent distribution is the same as the maximum likelihood distribution from the closure of the set of log-linear RF distributions.

S. D. Pietra, V. D. Pietra, and J. Lafferty, "Inducing features of random fields", IEEE PAMI, 1997.

Relationship between UGMs and other models



Feature-based potential representation in log-linear models

- Consider an edge potential $\phi_{s,t}(x_s, x_t)$ associated with two discrete variables x_s and x_t , both of which can take K values.
- Define a feature vector of length K^2 as follows:

$$f_{s,t}(x_s, x_t) = [\dots, 1(x_s = j, x_t = k), \dots]^T, \quad j, k = 1, \dots, K$$

with the associated weights:

$$\theta_{s,t} = [\dots, \log(\phi_{s,t}(x_s = j, x_t = k)), \dots]^T, \quad j, k = 1, \dots, K$$

- Then the **tabular potential** $\phi_{s,t}(x_s, x_t)$ can be represented as the log-linear form

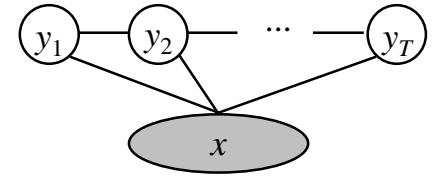
$$\phi_{s,t}(x_s, x_t) = \exp[\theta_{s,t}^T f_{s,t}(x_s, x_t)]$$

- Note: the log-linear form is more general because we can choose (or learn) the features.

Linear-chain CRFs

for sequence tagging, e.g. POS tagging, shallow parser, Chinese word segmentation, ...

$$p(y_{1:T} | x) \propto \exp \left\{ \sum_{t=1}^{T-1} \psi_t(y_t, y_{t+1}, x) + \sum_{t=1}^T \psi_t(y_t, x) \right\}$$



Log-linear representation of tabular potentials

$$p(y_{1:T} | x) \propto \exp \left\{ \sum_{t=1}^{T-1} \sum_i \lambda_i f_i(y_t, y_{t+1}, x, t) + \sum_{t=1}^T \sum_j \mu_j f_j(y_t, x, t) \right\}$$

Transition/edge features

$$\lambda_i f_i(y_t, y_{t+1}, x, t) = \lambda_i \cdot 1(y_t = \textit{prep}, y_{t+1} = \textit{non})$$

State/node features

$$\mu_j f_j(y_t, x, t) = \mu_j \cdot 1(y_t = \textit{prep}, x_t = \textit{on})$$

$$\mu_j f_j(y_t, x, t) = \mu_j \cdot 1(y_t = \textit{adv}, x_t \text{ ends in } \textit{ly})$$

Training of UGMs in general

$$p(x; \theta) = \frac{1}{Z(\theta)} \exp[Q(x; \theta)]$$

Normalization constant:

$$Z(\theta) = \sum_x \exp[Q(x; \theta)]$$

- Maximum likelihood (ML) training

The scaled log-likelihood of observed $\{x_i, i = 1, \dots, N\}$

$$l(\theta) \triangleq \frac{1}{N} \sum_{i=1}^N \log p(x_i; \theta) = \left[\frac{1}{N} \sum_{i=1}^N Q(x_i; \theta) \right] - \log Z(\theta)$$

$$\frac{\partial l(\theta)}{\partial \theta} = E_{\tilde{p}(x)} \left[\frac{\partial Q(x; \theta)}{\partial \theta} \right] - E_{p(x; \theta)} \left[\frac{\partial Q(x; \theta)}{\partial \theta} \right] = 0$$

Maximum Entropy

Expectation under

$$\text{empirical distribution } \tilde{p}(x) = \frac{1}{N} \sum_{i=1}^N 1(x = x_i)$$

Expectation under

$$\text{model distribution } p(x; \theta)$$

Training of UGMs - overview

- Roughly speaking, two types of approximate methods
- Gradient methods
 - Make explicit use of the gradient: Gradient descent, conjugate gradient, L-BFGS.
 - Stochastic approximation (SA)
 - Stochastic maximum likelihood (SML)
 - Persistent contrastive divergence (PCD)
- Lower bound methods
 - Generalized iterative scaling (GIS)
 - Improved iterative scaling (IIS)
 - Mostly studied in the context of maximum entropy (maxent) parameter estimation of log-linear models.
- In practice the gradient methods are shown to be much faster than the lower bound methods

Comparison on learning CRFs

- Div: the relative entropy between the fitted model and the training data
 - Iter: Iteration number
 - Evals: the number of calculating log-likelihood and gradient
 - Time: the total time.
- T. Tieleman, “Training restricted boltzmann machines using approximations to the likelihood gradient”, ICML 2008.
 - R. Malouf, “A comparison of algorithms for maximum entropy parameter estimation”, in Proc. Conference on Natural Language Learning (CoNLL), 2002.

Dataset	Method	Div.	Iter	Evals	Time (secs)
rules	gis	5.19×10^{-2}	1201	1202	23.04
	iis	5.14×10^{-2}	923	924	42.48
	steepest ascent	5.13×10^{-2}	212	331	6.16
	conjugate gradient (fr)	5.07×10^{-2}	74	196	3.74
	conjugate gradient (prp)	5.08×10^{-2}	63	154	2.87
	limited memory variable metric	5.07×10^{-2}	70	76	1.44
lex	gis	1.61×10^{-3}	370	371	36.29
	iis	1.52×10^{-3}	241	242	102.18
	steepest ascent	3.47×10^{-3}	1041	1641	139.10
	conjugate gradient (fr)	1.39×10^{-3}	166	453	39.03
	conjugate gradient (prp)	1.62×10^{-3}	150	382	32.46
	limited memory variable metric	1.49×10^{-3}	136	143	17.25
summary	gis	1.83×10^{-3}	1446	1447	125.46
	iis	1.07×10^{-3}	626	627	208.22
	steepest ascent	2.64×10^{-3}	1163	3503	227.30
	conjugate gradient (fr)	1.01×10^{-4}	175	948	60.91
	conjugate gradient (prp)	7.30×10^{-4}	93	428	27.81
	limited memory variable metric	3.98×10^{-5}	81	89	10.38
shallow	gis	3.57×10^{-2}	3428	3429	27103.62
	iis	3.50×10^{-2}	3216	3217	71053.24
	steepest ascent [†]	—	—	—	—
	conjugate gradient (fr)	2.91×10^{-2}	1094	6056	46958.87
	conjugate gradient (prp)	4.13×10^{-2}	421	2170	16477.84
	limited memory variable metric	3.26×10^{-2}	429	444	3408.30

Training of log-linear models

$$p(x; \theta) = \frac{1}{Z(\theta)} \exp \left[\sum_C \theta_C^T f_C(x) \right] \quad \text{where } C \text{ indexes the cliques.}$$

$$\frac{\partial l(\theta)}{\partial \theta_C} = E_{\tilde{p}(x)}[f_C(x)] - E_{p(x; \theta)}[f_C(x)] = 0 \quad \text{Statistics matching}$$

Empirical statistics of features

Expected statistics of features

- $l(\theta)$ is convex in θ , so it has a unique global maximum which we can find using gradient-based optimizers. 😊
- The exact calculation of the gradient is intractable in general, involving high-dimensional integration. 😞

课程章节

- 第一章 图模型的表示理论 (2)
 - Semantics (DGM, UGM)
 - HMM, CRF
- 第二章 图模型的推理理论 (4)
 - 精确推理: variable-elimination, cluster-tree, triangulate
 - 连续变量: Kalman
 - 采样近似: sampling
 - 变分近似: variational
- 第三章 图模型的学习理论 (2)
 - 参数学习: maxlikelihoodEstimate, RFLearning, BayesEstimate
 - 结构学习: StructureLearning

			pgm-2 hmm-crf ✓	pgm-4 kalman ✓
	pgm-1 semantics ✓		pgm-3 exact ✓	pgm-5 sampling ✓
pgm-6 variational ✓	pgm-8 Bayesian			
pgm-7 ML ✓				